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Content-Guidance in Formal Problem Solving Processes

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Some Background (1)

- Vienna Circle: (degenerated to) a priori methodology
- Historicism (Kuhn, ...): relativism
- today: scientific problem-solving is content-guided "what we have learned, including what we have learned about how to learn" (Shapere)

all possibilities / historicism

Aim of this paper:

- formal approach to problem solving
- in which there is large room for content-guidance

 $(\Rightarrow example)$

Outline

Some Background

Elements of a psp backbone procedure rules instructions marking

An Example of the Backbone

Adaptive logics

Some Extra-Logical Extensions

Comments

Some Background (2)

direct sources of inspiration:

- philosophy of science/epistemology:
 - problem solving: Kuhn, Laudan, *Nickles*, ...
 'contextual': specific certainties, relevant data,
 - methodological instructions, ... for each problem
- logic:
 - procedures prospective dynamics
 - adaptive logics
 - erotetic logic (varying on Wiśniewski)

problem determined by (changing) constraints

- conditions on solution
- methodological instructions / heuristics / examples
- ► certainties (conceptual system, ...)

Some Background (3)

some elements of the plot:

- aim: explication for problem solving processes (psps)
- backbone:
- solve $\{?\{A, \sim A\}\}$ by **CL**-deriving A or $\sim A$ from Γ
- empirical means: observation and experiment guided by psp
- new available information (not originally seen as relevant) guided by psp
- adaptive logics: *corrective:* handling inconsistency (and similar), ambiguity, vagueness, ... *ampliative:* inductive generalization, abduction, ...

control defeasible inferences by conditions and marking

model-based reasoning (mainly future research)

Elements of a psp backbone

lines of psp

- ▶ problem lines: example {?{p ∨ q, ~p ∨ q}, ?{r, ~r}} problem = non-empty set of questions
- declarative lines
- · conditional: $[B_1, \ldots, B_n] A$
- · unconditional: $[\emptyset] A$, viz. A

Some Background (4)

from the general plot (consolations?)

- in the end all knowledge defeasible
- going through different 'contexts' $\Rightarrow \begin{cases} conceptual change \\ generation of new concepts \end{cases}$
- many ampliative mechanisms
- (abduction overestimated)
- independent of ontological debates

psp

- stage of a psp: sequence of lines
- psp: chain of stages

governed by procedure

next stage: add new line + apply marking definitions

. . .

- procedure (set of instructions) • rule of inference: to derive A from B_1, \ldots, B_n
- instruction: rule of inference + permissions/obligations permissions/obligations depend on the present stage (lines + marks)
- below: instructions (including the rules)

varying on Smullyan

a	a ₁	a ₂	b	b ₁	b ₂
$A \wedge B$	A	В	$\sim (A \wedge B)$	*A	*B
$A \equiv B$	$A \supset B$	$B \supset A$	$\sim (A \equiv B)$	$\sim (A \supset B)$	$\sim (B \supset A)$
$\sim (A \lor B)$	*A	*B	$A \lor B$	A	В
$\sim (A \supset B)$	Α	*B	$A \supset B$	*A	В
~~A	Α	Α			

complement of A: *A = B if $A = \sim B$; otherwise $*A = \sim A$

a	a ₁	a ₂	b	\mathfrak{b}_1	\mathfrak{b}_2
$A \wedge B$	A	В	$\sim (A \wedge B)$	*A	*B
$A \equiv B$	$A \supset B$	$B \supset A$	$\sim (A \equiv B)$	$\sim (A \supset B)$	$\sim (B \supset A)$
$\sim (A \lor B)$	*A	*B	$A \lor B$	А	В
$\sim (A \supset B)$	A	*B	$A \supset B$	*A	В
$\sim \sim A$	A	A			

formula analysing rules:

[Δ] a				
[Δ] a ₁	[Δ] a ₂			

 $\frac{[\Delta] \mathfrak{b}}{[\Delta \cup \{*\mathfrak{b}_2\}] \mathfrak{b}_1 \ [\Delta \cup \{*\mathfrak{b}_1\}] \mathfrak{b}_2}$

condition analysing rules:

 $\frac{[\Delta \cup \{\mathfrak{a}\}]A}{[\Delta \cup \{\mathfrak{a}\}, \mathfrak{a}_2\}]A} \qquad \frac{[\Delta \cup \{\mathfrak{b}\}]A}{[\Delta \cup \{\mathfrak{b}\}]A \quad [\Delta \cup \{\mathfrak{b}_2\}]A}$

a	a ₁	a ₂	b	b ₁	b ₂
$A \wedge B$	A	В	$\sim (A \wedge B)$	*A	*B
$A \equiv B$	$A \supset B$	$B \supset A$	$\sim (A \equiv B)$	$\sim (A \supset B)$	$\sim (B \supset A)$
$\sim (A \lor B)$	*A	*B	$A \lor B$	Α	В
$\sim (A \supset B)$	A	*B	$A \supset B$	*A	В
~~ <i>A</i>	A	Α			

positive part relation

1. pp(*A*, *A*).

- 2. $pp(A, \mathfrak{a})$ if $pp(A, \mathfrak{a}_1)$ or $pp(A, \mathfrak{a}_2)$.
- 3. pp(A, b) if $pp(A, b_1)$ or $pp(A, b_2)$.
- 4. If pp(A, B) and pp(B, C), then pp(A, C).

The instructions

Main	Start a psp with the line: 1 $\{?\{M, \sim M\}\}$	Main
Target	•	Inmarked problem line, and A ember of P, then one may add: Target
Prem	If A is an unmarked targe one may add:	t, $B \in \Gamma$, and pp(A, B), then

k B Prem

Formula analysing rules:

$[\Delta] \alpha$		$[\Delta] \beta$			
$[\Delta] \alpha_1$	[Δ] α ₂		$\left[\Delta \cup \{*\beta_2\}\right]\beta_1$	$\left[\Delta \cup \{*\beta_1\}\right]\beta_2$	

FAR If *C* is an unmarked target, $[\Delta] A$ is the formula of an unmarked line *i*, $[\Delta] A / [\Delta \cup \Delta'] B$ is a formula analysing rule, and pp(*C*, *B*), then one may add: *k* $[\Delta \cup \Delta'] B$ *i*; R in which R is the name of the formula analysing rule.

Condition analysing rules:

$[\Delta \cup \{\alpha\}] A$	$[egin{smallmatrix} \Delta \cup \{eta\}] eta$		
$[\Delta \cup \{\alpha_1, \alpha_2\}] A$	$[\Delta \cup \{\beta_1\}] \boldsymbol{A}$	$[\Delta \cup \{\beta_2\}] A$	

CAR If *A* is an unmarked target, $[\Delta \cup \{B\}]A$ is the formula of an unmarked line *i*, and $[\Delta \cup \{B\}]A / [\Delta \cup \Delta']A$ is a condition analysing rule, then one may add: $k \quad [\Delta \cup \Delta']A \quad i; \mathbb{R}$ in which R is the name of the condition analysing rule.

Eliminate some problems without answering them:

EM0 If $[\Delta \cup \{*A\}] A$ is the formula of a line *i* that is neither R-marked nor I-marked, then one may add: k $[\Delta] A$ *i*; EM0 EM If A is an unmarked target, $[\Delta \cup \{B\}] A$ and $[\Delta' \cup \{\sim B\}] A$ are the respective formulas of the unmarked or only D-marked lines *i* and *j*, and $\Delta \subseteq \Delta'$ or $\Delta' \subseteq \Delta$, then one may add:

 $k \qquad [\Delta \cup \Delta'] A \qquad \qquad i, j; EM$

eliminate solved questions from a problem and summarize remaining problems (and paths):

Trans If A is an unmarked target, and $[\Delta \cup \{B\}] A$ and $[\Delta'] B$ are the respective formulas of the at most S-marked lines *i* and *j*, then one may add:

 $k \qquad [\Delta \cup \Delta'] A \qquad \qquad i, j; \text{ Trans}$

handle derived problems:

DP If A is an unmarked target from problem line i and $[B_1, \ldots, B_n]$ A is the formula of an unmarked line *j*, then one may add:

k $\{?\{B_1, \sim B_1\}, \ldots, ?\{B_n, \sim B_n\}\}$ *i*, *j*; DP

Remark:

no instruction for applying EFQ

in view of the intended applications (deriving predictions, explanations, etc.)

Marking definitions

redundant lines are R-marked:

Definition

An at most S-marked declarative line *i* that has $[\Delta] A$ as its formula is R-marked at a stage iff, at that stage, $[\Theta]$ A is the formula of a line for some $\Theta \subset \Delta$.

Definition

An unmarked problem line *i* is R-marked at a stage iff, at that stage, a direct answer A of a question of line i is the formula of a line.

inoperative lines are I-marked (not useful for extant problem):

Definition

An at most S-marked target line that has [A] A as its formula is I-marked at a stage iff every problem line from which A is a target is marked at that stage.

Definition

An at most S-marked resolution line of which $[\Delta^1] A^1$ is the formula and $\Delta^1 \neq \emptyset$ is *I-marked* at a stage iff, at that stage, for every grounded target sequence $\langle [\Delta^n] A^n, \dots, [\Delta^1] A^1 \rangle$,

- (i) some target $[A^i] A^i$ ($1 \le i \le n$) is marked, or
- (ii) $\{A^n, \dots, A^1\} \cap \Delta^1 \neq \emptyset$, or (iii) $\Delta^1 \cup \dots \cup \Delta^n \cup \Gamma_s^\circ$ is flatly inconsistent.

Definition

An unmarked problem line is I-marked iff no unmarked resolution line generates it.

for all consistent Γ:

if $\Gamma \vdash A$, then the procedure applied to Γ and $\{?\{A, \sim A\}\}$ results in the answer A,

and

if $\Gamma \nvDash A$, then the procedure applied to Γ and $\{?\{A, \sim A\}\}$ stops without the main problem being answered or results in the answer $\sim A$.

· target from a problem line

- resolution line
- · direct target from
- · target sequence
- · grounded target sequence

Dead end lines are D-marked (no further action from such line)

- A is a dead end (A is literal and not positive part of
- premise)
- CAR-descendant of $[\Delta] B$

Definition

An at most S-marked resolution line with formula $[\Delta] A$ is D-marked at a stage iff some $B \in \Delta$ is a dead end or, at that stage, all CAR-descendants of $[\Delta] A$ occur in the psp and are D-marked.

Definition

An at most S-marked target line with formula [A] A is D-marked at a stage iff A is a dead end or no further action can be taken in view of target A.

Speed up the procedure by S-marks

 Γ_s° union of the Γ and of the set of the conditionless formulas that occur at stage s of the psp

Definition

A R-unmarked resolution line in which $[\Delta^1] A^1$ is derived is S-marked iff

- (i) $\Delta^1 \cap \Gamma_s^{\circ} \neq \emptyset$, or
- (ii) for some target sequence $\langle [\Delta^n] A^n, \dots, [\Delta^1] A^1 \rangle$, $\{A^n\} \cup \Delta^1$ is flatly inconsistent whereas Δ^1 is not flatly inconsistent, or
- (iii) $\Delta_1 \subset \Delta^n \cup \ldots \cup \Delta^2$ for some target sequence $\langle [\Delta^n] A^n, \ldots, [\Delta^1] A^1 \rangle.$

instruction: operate on S-marked lines before doing anything else

An Example of the Backbone

main problem:	?{ p ∨	q,~(p	∨ q)}
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premise set: { \sim *s*, \sim *u* \lor *r*, (*r* \land *t*) \lor *s*, (*q* \lor *u*) \supset (\sim *t* \lor *q*), *t* \supset *u*}

logic: \mathbf{CL}^- + an erotetic logic (fixed by the procedure)

procedure: prospective dynamics + problems

$\{\sim s, \sim u \lor r, (r \land t) \lor s, (q \lor u) \supset (\sim t \lor q), t \supset u\}$

1	$\{?\{\boldsymbol{p} \lor \boldsymbol{q}, \sim (\boldsymbol{p} \lor \boldsymbol{q})\}\}$	Main	
6	$[q] p \lor q$	4; C∨E	
15 16 17 18 19 20	$[u, t] q$ $\{?\{u, \sim u\}, ?\{t, \sim t\}\}$ $[t] t$ $(r \land t) \lor s$ $[\sim s] r \land t$ $[\sim s] t$ $\{?\{s, \sim s\}\}$ $[\sim s] \sim s$ $\sim s$ t $[u] q$ $\{?\{u, \sim u\}\}$	13; ∨E 8, 14; DP Target Prem 17; ∨E 18; ∧E 16, 19; DP Target Prem 19, 22; Trans 14, 23; Trans 8, 24; DP	S ²³ R ²⁴ R ²³ R ²³ S ²² R ²³ R ²² R ²²

1, 6, 23–25

Adaptive logics (only Standard Format)

characterization

- Iower limit logic LLL monotonic, compact, ... logic
- set of abnormalities Ω characterized by a (possibly restricted) logical form
- ► strategy
- Reliability, Minimal Abnormality, ...

upper limit logic:

syntax: **ULL** = **LLL** + axiom/rule semantics: the **LLL**-models that verify no abnormality

general idea behind adaptive logics:

 $Cn_{AL}(\Gamma) : Cn_{LLL}(\Gamma) +$ what follows if as many members of Ω are false as the premises permit

Example: logic of inductive generalization: IL^m

- ► lower limit logic: CL
- set of abnormalities: $\Omega = \{ \exists A \land \exists \sim A \mid A \in \mathcal{F}^{\circ} \}$
- strategy: Minimal Abnormality

upper limit logic:

 $\mathsf{UCL} = \mathsf{CL} + \exists \alpha \mathsf{A}(\alpha) \supset \forall \alpha \mathsf{A}(\alpha)$

semantically: the uniform **CL**-models ($v(\pi^r) \in \{\emptyset, D^{(r)}\}$)

ampliative adaptive logic (if CL is the standard)

$\{\sim s, \sim u \lor r, (r \land t) \lor s, (q \lor u) \supset (\sim t \lor q), t \supset u\}$

1 2	$\{ ? \{ p \lor q, \sim (p \lor q) \} \} \\ [\sim (p \lor q)] \sim (p \lor q) $	Main Target	D ³
2	$[\sim(p \lor q)] \sim (p \lor q)$ $[\sim p, \sim q] \sim (p \lor q)$	iaigei 2; C∼∀E	D ³
4	$[p \lor q] p \lor q$	Target	2
5	$[p] p \lor q$	4; Č∨E	D^5
6	$[q] p \lor q$	4; C∨E	
7	$\{?\{q, \sim q\}\}$	4, 6; DP	
8	[<i>q</i>] <i>q</i>	Target	
9	$(q \lor u) \supset (\sim t \lor q)$	Prem	
10	$[q \lor u] \sim t \lor q$	9;	
11	$[q] \sim t \lor q$	10; C∨E	
12	[q, t] q	11; ∨E	1 ¹²
13	$[u] \sim t \lor q$	10; C∨E	
14	[<i>u</i> , <i>t</i>] <i>q</i>	13; ∨E	
15	$\{?\{u, \sim u\}, ?\{t, \sim t\}\}$	8, 14; DP	
16	[<i>t</i>] <i>t</i>	Target	

1, 6, 14–16

$\{\sim s, \sim u \lor r, (r \land t) \lor s, (q \lor u) \supset (\sim t \lor q), t \supset u\}$

1	$\{?\{\boldsymbol{p} \lor \boldsymbol{q}, \sim (\boldsymbol{p} \lor \boldsymbol{q})\}\}$	Main	R ³¹
6	$[q] p \lor q$	4; C∨E	S ³⁰ R ³¹
23	t	19, 22; Trans	
24	[<i>u</i>] <i>q</i>	14, 23; Trans	C29 B30
25		8, 24; DP	R ²⁹
		, ,	R ²⁹
26	[<i>u</i>] <i>u</i>	Target	H ₂ 2
27	$t \supset u$	Prem	
28	[t] u	27; ⊃E	S ²⁸ R ²⁹
29	u	23, 28; Trans	
30	q	24, 29; Trans	
31	$p \lor q$	6, 30; Trans	

problem solved

Example: the inconsistency-adaptive CLuN^r

- ► lower limit logic: CLuN
- set of abnormalities: $\Omega = \{ \exists (A \land \sim A) \mid A \in \mathcal{F} \}$
- strategy: Reliability

upper limit logic: $CL = CLuN + (A \land \sim A) \supset B$ semantically: the CLuN-models that verify no inconsistency

corrective adaptive logic (if CL is the standard)

standard format provides

- proofs
- semantics
- most of metatheory (including soundness and completeness)
- prospective dynamics (published for Reliability)

further examples (relevant for philosophy of science)

- many other inconsistency-handling (+ other logical symbols)
- ambiguity-adaptive
- vagueness-adaptive
- corrective deontic logics
- paraconsistent compatibility
- <u>►</u> ...
- plausibility-adaptive
- compatibility
- diagnosis
- abduction
- analogies, metaphors
- erotetic evocation/implication (problem solving)
- **۱**

Some Extra-Logical Extensions (2)

bringing in available information (formerly judged irrelevant)

one tries to solve problem from theory T and set of data later a theory T' turns out to be relevant

(because a target is a positive part of an axiom of T')

psp guides (which further theories are relevant?)

Comments (1)

framework that contains open slots

these make content guidance possible

but the framework is formal

prospective dynamics pushes the 'logical' part of the heuristics into the proof

part of remaining heuristics is fixed by procedure

still remaining heuristics

Comments (3)

content-guided

- ▶ ./.
- ' 'guesses': world-view, personal constraints, ..., blind (which guesses useful: determined by disjunctions of abnormalities)
- (extra logical origin; logic guides handling of the guesses)local selection of adaptive logics
- (abd./ind.; inconsistency; replace lower limit logic; plausibilities; ...)
- heuristics of psp
 - road followed to derive conclusion
 - observation / experiment / theoretical derivation
 - [use of models]

to be decided in view of what was learned about world/learning in specific domain/context

Some Extra-Logical Extensions (1)

answerable questions

 $\mathbb A$ is a set of couples $(\Delta:\mathcal Q)$ in which Δ is a set of statements and $\mathcal Q$ is a question

idea: if the members of Δ are true, Q can be answered by observational/experimental means (not Hintikka's oracle)

New If *A* is an unmarked target, pp(A, B) for some direct answer *B* of *Q*, ($\Delta : Q$) and all members of Δ occur in the fpsp, then one may add, for some direct answer *C* of *Q*: *k C i*; New

psp guides (which observations/experiments should be carried out)

Some Extra-Logical Extensions (3)

plausible conjectures

where A is an abnormality, introduce $\Diamond^i A$ or $\Diamond^i \neg A$

- basis: worldview, personal constraint, study of situation, blind guess
- thus reducing a disjunction of abnormalities
- defeasibly obtaining more consequences (plausibility-adaptive logic)

psp guides (which disjunctions of abnormalities may be reduced?)

. . .

Comments (2)

content-guided

- 'language' of a scientific discipline (not typical)
- adaptive logics validate applications of rules that transcend the lower limit logic
- multiplicity of adaptive logics for every purpose (to be justified)
- multiplicity of erotetic logics (to be justified)
- multiplicity of procedures for prospective dynamics (to be justified)
- take background theories serious + several forms of defeasibility
- ▶ ./.

Comments (4)

conclusion

framework that contains open slots

these make content guidance possible

but the framework is formal

status of the approach itself: provisional hypothesis